

THIRD EDITION

Electric Motors and Systems Frank D. Petruzella

THIRD EDITION

Electric Motors and Control Syster

Frank D. Petruz





ELECTRIC MOTORS AND CONTROL SYSTEMS

Published by McGraw-Hill Education, 2 Penn Plaza, New York, NY 10121. Copyright ©2020 by McGraw-Hill Education. All rights reserved. Printed in the United States of America. No part of this publication may be reproduced or distributed in any form or by any means, or stored in a database or retrieval system, without the prior written consent of McGraw-Hill Education, including, but not limited to, in any network or other electronic storage or transmission, or broadcast for distance learning.

Some ancillaries, including electronic and print components, may not be available to customers outside the United States.

This book is printed on acid-free paper.

1 2 3 4 5 6 7 8 9 LWI 21 20 19

ISBN 978-1-260-57014-4 MHID 1-260-57014-2

Cover Image: Mr. B-King/Shutterstock

All credits appearing on page or at the end of the book are considered to be an extension of the copyright page.

The Internet addresses listed in the text were accurate at the time of publication. The inclusion of a website does not indicate an endorsement by the authors or McGraw-Hill Education, and McGraw-Hill Education does not guarantee the accuracy of the information presented at these sites.

ABOUT THE AUTHOR

Frank D. Petruzella has extensive practical experience in the electrical motor control field, as well as many years of experience teaching and authoring textbooks. Before becoming a full-time educator, he was employed as an apprentice and electrician in areas of electrical installation and maintenance. He holds a Master of Science degree from Niagara University, a Bachelor of Science degree from the State University of New York College–Buffalo, as well as diplomas in Electrical Power and Electronics from the Erie County Technical Institute.

One unique feature with all of his texts is that they are all supported with the latest in related computer simulation software. Working in conjunction with National Instruments for Multisim, CMH Software for Constructor, and The Learning Pit for LogixPro, he has developed program files directly related to circuits explained in the text.

BRIEF CONTENTS

	About the Author iii					
	Preface ix					
	Acknowledgments xi					
	Walk-through xii					
Chapter	1 Safety in the Workplace 1					
	PART 1 Protecting against Electrical Shock 1					
	PART 2 Grounding—Lockout—Codes 9					
Chapter	2 Understanding Electrical Drawings 16					
	PART 1 Symbols—Abbreviations—Ladder Diagrams 16					
	PART 2 Wiring—Single Line—Block Diagrams 24					
	PART 3 Motor Terminal Connections 28					
	PART 4 Motor Nameplate and Terminology 37					
	PART 5 Manual and Magnetic Motor Starters 42					
Chapter 3 Motor Transformers and Distribution Systems 47						
	PART 1 Power Distribution Systems 47					
	PART 2 Transformer Principles 57					
	PART 3 Transformer Connections and Systems 62					
Chapter 4 Motor Control Devices 72						
	PART 1 Manually Operated Switches 72					
	PART 2 Mechanically Operated Switches 80					
	PART 3 Sensors 86					
	PART 4 Actuators 98					
Chapter 5 Electric Motors 105						
	PART 1 Motor Principle 105					
	PART 2 Direct Current Motors 110					
	PART 3 Three-Phase Alternating Current Motors 122					
	PART 4 Single-Phase Alternating Current Motors 131					
	PART 5 Alternating Current Motor Drives 136					
	PART 6 Motor Selection 139					

PART 7 Motor Installation 146

PART 8 Motor Maintenance and Troubleshooting 151

Chapter 6 Contactors and Motor Starters 158

PART 1 Magnetic Contactor 158

PART 2 Contactor Ratings, Enclosures, and Solid-State Types 169

PART 3 Motor Starters 175

Chapter 7 Relays 186

PART 1 Electromechanical Control Relays 186

PART 2 Solid-State Relays 191

PART 3 Timing Relays 195

PART 4 Latching Relays 203

PART 5 Relay Control Logic 207

Chapter 8 Motor Control Circuits 211

PART 1 NEC Motor Installation Requirements 211

PART 2 Motor Starting 218

PART 3 Motor Reversing and Jogging 231

PART 4 Motor Stopping 238

PART 5 Motor Speed 242

Chapter 9 Motor Control Electronics 245

PART 1 Semiconductor Diodes 245

PART 2 Transistors 251

PART 3 Thyristors 259

PART 4 Integrated Circuits (ICs) 265

Chapter 10 Adjustable-Speed Drives and PLC Installations 275

PART 1 AC Motor Drive Fundamentals 275 PART 2 VFD Installation and Programming Parameters 283 PART 3 DC Motor Drive Fundamentals 297 PART 4 Programmable Logic Controllers (PLCs) 304 Appendix 318 Index I-1



CONTENTS

About the Author iii Preface ix Acknowledgments xi Walk-through xii

Chapter 1 Safety in the Workplace 1

PART 1 Protecting against Electrical Shock 1 Electrical Shock 1 Arc Flash Hazards 4 Personal Protective Equipment 5 Machine Safety 7 Safety Light Curtains 7 Safety Interlock switches 7 Emergency Stop Controls 8 Safety Laser Scanners 8 PART 2 Grounding—Lockout—Codes 9 Grounding and Bonding 9 Lockout and Tagout 11 Electrical Codes and Standards 12

Chapter 2 Understanding Electrical Drawings 16

PART 1 Symbols—Abbreviations—Ladder Diagrams 16 Motor Symbols 16 Abbreviations for Motor Terms 17 Motor Ladder Diagrams 17
PART 2 Wiring—Single Line—Block Diagrams 24 Wiring Diagrams 24 Single-Line Diagrams 26 Block Diagrams 26

Riser Diagrams 27

PART 3 Motor Terminal Connections 28

Motor Classification 28

DC Motor Connections 28

AC Motor Connections 30

PART 4 Motor Nameplate and Terminology 37

NEC Required Nameplate Information 37

Optional Nameplate Information 39

Guide to Motor Terminology 41

PART 5 Manual and Magnetic Motor Starters 42

Manual Starter 42

Magnetic Starter 43

Chapter 3 Motor Transformers and Distribution Systems 47

PART 1 Power Distribution Systems 47 **Transmission Systems 47** Unit Substations 48 Distribution Systems 50 Power Losses 51 Switchboards and Panelboards 52 Motor Control Centers (MCCs) 54 **Electrical Grounding 56** PART 2 Transformer Principles 57 **Transformer Operation 57** Transformer Voltage, Current, and Turns Ratio 58 Transformer Power Rating 60 **Transformer Performance 61** PART 3 Transformer Connections and Systems 62 **Transformer Polarity 62** Single-Phase Transformers 63 **Three-Phase Transformers 65 Instrument Transformers 67 Transformer Testing 69**

Chapter 4 Motor Control Devices 72

PART 1 Manually Operated Switches 72 Primary and Pilot Control Devices 72 **Toggle Switches 73** Pushbutton Switches 73 Pilot Lights 77 **Tower Light Indicators 78** Selector Switch 78 Drum Switch 79 PART 2 Mechanically Operated Switches 80 Limit Switches 80 **Temperature Control Devices 82** Pressure Switches 83 Float and Flow Switches 84 PART 3 Sensors 86 **Proximity Sensors 86** Photoelectric Sensors 89 Hall Effect Sensors 91 Ultrasonic Sensors 92 **Temperature Sensors 93** Velocity and Position Sensors 95 Flow Measurement 96 Magnetic Flowmeters 97 PART 4 Actuators 98 **Relays 98** Solenoids 99 Solenoid Valves 100 Stepper Motors 101 Servo Motors 102

Chapter 5 Electric Motors 105

PART 1 Motor Principle 105 Magnetism 105 Page vi

Electromagnetism 106 Generators 106 Motor Rotation 107 PART 2 Direct Current Motors 110 Permanent-Magnet DC Motor 110 Series DC Motor 112 Shunt DC Motor 113 Compound DC Motor 114 Direction of Rotation 115 Motor Counter Electromotive Force (CEMF) 116 Armature Reaction 117 Speed Regulation 117 Varying DC Motor Speed 118 DC Motor Drives 119 **Brushless DC Motors 120** PART 3 Three-Phase Alternating Current Motors 122 Rotating Magnetic Field 122 Induction Motor 124 Squirrel-Cage Induction Motor 124 Wound-Rotor Induction Motor 128 Three-Phase Synchronous Motor 129 PART 4 Single-Phase Alternating Current Motors 131 Split-Phase Motor 131 Split-Phase Capacitor Motor 133 Shaded-Pole Motor 135 Universal Motor 135 PART 5 Alternating Current Motor Drives 136 Variable-Frequency Drive 136 Inverter Duty Motor 139 PART 6 Motor Selection 139 Mechanical Power Rating 140 Current 140 Code Letter 140 **Design Letter 140**

Efficiency 140 Energy-Efficient Motors 141 Frame Size 141 Frequency 141 Full-Load Speed 141 Load Requirements 141 Motor Temperature Ratings 142 Duty Cycle 143 Torque 143 Motor Enclosures 143 Metric Motors 144 PART 7 Motor Installation 146 Foundation 146 Mounting 146 Motor and Load Alignment 146 Motor Bearings 147 **Electrical Connections 148** Grounding 149 Conductor Size 149 Voltage Levels and Balance 149 **Built-in Thermal Protection 150** PART 8 Motor Maintenance and Troubleshooting 151 Motor Maintenance 151 **Troubleshooting Motors 152 Chapter 6**

Contactors and Motor Starters 158

PART 1 Magnetic Contactor 158 Switching Loads 159 Capacitor Switching Contactors 162 Contactor Assemblies 163 Arc Suppression 166 PART 2 Contactor Ratings, Enclosures, and Solid-State Types 169 NEMA Ratings 169 IEC Ratings 170 Contactor Enclosures 171 Solid-State Contactor 172 PART 3 Motor Starters 175 Magnetic Motor Starters 175 Motor Overcurrent Protection 176 Motor Overload Relays 178 NEMA and IEC Symbols 182

Chapter 7 Relays 186

PART 1 Electromechanical Control Relays 186 **Relay Operation 186 Relay Applications 188 Relay Styles and Specifications 188** Interposing Relay 190 PART 2 Solid-State Relays 191 **Operation 191 Specifications 193** Switching Methods 194 PART 3 Timing Relays 195 Motor-Driven Timers 195 **Dashpot Timers 196** Solid-State Timing Relays 196 **Timing Functions 197** Multifunction and PLC Timers 201 PART 4 Latching Relays 203 Mechanical Latching Relays 203 Magnetic Latching Relays 204 Latching Relay Applications 204 Alternating Relays 204 PART 5 Relay Control Logic 207 Control Circuit Inputs and Outputs 207 AND Logic Function 207 **OR Logic Function 207 Combination Logic Functions 208**

Page vii

NOT Logic Function 208 NAND Logic Function 208 NOR Logic Function 209

Chapter 8 Motor Control Circuits 211

PART 1 NEC Motor Installation Requirements 211 Sizing Motor Branch Circuit Conductors 212 **Branch Circuit Motor Protection 212** Selecting a Motor Controller 215 Disconnecting Means for Motor and Controller 215 Providing a Control Circuit 216 PART 2 Motor Starting 218 Full-Voltage Starting of AC Induction Motors 218 Reduced-Voltage Starting of Induction Motors 223 DC Motor Starting 229 PART 3 Motor Reversing and Jogging 231 **Reversing of AC Induction Motors 231** Reversing of Single-Phase Motors 234 Reversing of DC Motors 236 Jogging 236 PART 4 Motor Stopping 238 Plugging and Antiplugging 238 **Dynamic Braking 240** DC Injection Braking 240 **Electromechanical Friction Brakes 241** PART 5 Motor Speed 242 Multispeed Motors 242 Wound-Rotor Motors 243

Chapter 9 Motor Control Electronics 245

PART 1 Semiconductor Diodes 245 Diode Operation 245 Rectifier Diode 246

Zener Diode 249 Light-Emitting Diode 249 Photodiodes 250 Inverters 251 PART 2 Transistors 251 **Bipolar Junction Transistor (BJT) 252** Field-Effect Transistor 254 Metal Oxide Semiconductor Field-Effect Transistor (MOSFET) 255 Insulated-Gate Bipolar Transistor (IGBT) 257 PART 3 Thyristors 259 Silicon-Controlled Rectifiers (SCRs) 259 Triac 262 Electronic Motor Control Systems 264 PART 4 Integrated Circuits (ICs) 265 Fabrication 265 **Operational Amplifier ICs 266** 555 Timer IC 267 **Microcontroller 268** Electrostatic Discharge (ESD) 270 **Digital Logic 270**

Chapter 10 Adjustable-Speed Drives and PLC Installations 275

PART 1 AC Motor Drive Fundamentals 275
Variable-Frequency Drives (VFDs) 276
Volts per Hertz Drive 280
Flux Vector Drive 281
PART 2 VFD Installation and Programming Parameters 283
Selecting the Drive 283
Line and Load Reactors 284
Location 284
Enclosures 284
Mounting Techniques 285
Operator Interface 285
Electromagnetic Interference 285

Page viii

Grounding 286 **Bypass Contactor 286 Disconnecting Means 287** Motor Protection 287 Braking 288 Ramping 289 Control Inputs and Outputs 289 Motor Nameplate Data 292 Derating 292 Types of Variable-Frequency Drives 293 **PID Control 294** Parameter Programming 294 **Diagnostics and Troubleshooting 295** PART 3 DC Motor Drive Fundamentals 297 **Applications 297** DC Drives—Principles of Operation 297 Single-Phase Input—DC Drive 299 Three-Phase Input—DC Drive 300 Field Voltage Control 300 Nonregenerative and Regenerative DC Drives 301 Parameter Programming 302 PART 4 Programmable Logic Controllers (PLCs) 304 PLC Sections and Configurations 304 Ladder Logic Programming 306 **Programming Timers 309 Programming Counters 310 Troubleshooting 313**

Appendix 318 Index I-1

PREFACE

This book has been written for a course of study that will introduce the reader to a broad range of motor types and control systems. It provides an overview of electric motor operation, selection, installation, control, and maintenance. Every effort has been made to present the most up-to-date information, reflecting the current needs of the industry.

The broad-based approach taken makes this text viable for a variety of motor and control system courses. Content is suitable for colleges, technical institutions, and vocational/technical schools as well as apprenticeship and journeymen training. Electrical apprentices and journeymen will find this book to be invaluable because of National Electrical Code references as well as information on maintenance and troubleshooting techniques. Personnel involved in motor maintenance and repair will find the book to be a useful reference text.

The text is comprehensive! It includes coverage of how motors operate in conjunction with their associated control circuitry. Both older and newer motor technologies are examined. Topics covered range from motor types and controls to installing and maintaining conventional controllers, electronic motor drives, and programmable logic controllers.

Features you will find unique to this motors and controls text include:

Self-Contained Chapters. Each chapter constitutes a complete and independent unit of study. All chapters are divided into parts designed to serve as individual lessons. Instructors can easily pick and choose chapters or parts of chapters that meet their particular curriculum needs.

How Circuits Operate. When understanding the operation of a circuit is called for, a bulleted list is used to summarize its operation. The lists are used in place of paragraphs and are especially helpful for explaining the sequenced steps of a motor control operation.

Integration of Diagrams and Photos. When the operation of a piece of equipment is illustrated by means of a diagram, a photo of the device is included. This feature is designed to increase the level of recognition of devices associated with motor and control systems.

Troubleshooting Scenarios. Troubleshooting is an important element of any motors and controls course. The chapter troubleshooting scenarios are designed to help students with the aid of the instructor to develop a systematic approach to troubleshooting.

Discussion and Critical Thinking Questions. These open-ended questions are designed to give students an opportunity to reflect on the material covered in the chapter. In most cases, they allow for a wide range of responses and provide an opportunity for the student to share more than just facts.

The following content has been added to the chapters listed below:

- Chapter 1 Safety light curtains
 - Safety interlock switches
 - Emergency stop controls
 - Safety laser scanners

Chapter 2 - Comparison of common motor NEMA and IEC symbols

- Riser diagrams
- Dual voltage three-phase motor connections
- IEC three-phase motor connections
- IEC 2-wire and 3-wire control circuits
- Chapter 3 Motor control center three-phase full-voltage starter bucket
 - Electrical grounding
 - Transformer testing

Chapter 4 - IEC break-make pushbutton control circuit

- Two motor emergency stop control circuit
- Signal light towers
- Alternating pumping operation and control circuit
- Comparison of the features and application of sensors
- Chapter 5 DC brushless motor operation and applications
- **Chapter 6** Capacitor switching contactor operation and applications
 - DC inverter power contactors
- Chapter 7 Interposing relay operation and applications
 - Analog-switching relay operation and applications
 - Conveyor motor warning signal control circuit
 - Timed and instantaneous relay timer contacts
 - One-shot timer solenoid control circuit
 - Symmetrical recycle timer flasher circuit

Chapter 8 - Three motor sequential motor starting interlocking circuit.

- Two motor sequential motor stopping interlocking circuit.
- Three-phase motor selector jogging circuit.
- Zero-speed switch operation.
- Antiplugging executed using time-delay relays.

Chapter 9 - Inverter applications and output waveforms.

- Building blocks of an electronic motor control system.
- Three-wire sourcing and sinking sensor connections.

Page x

Chapter 10 - Analog versus digital signals.

- 4–20 mA control loop.
- PLC processor module troubleshooting.
- PLC input module troubleshooting.
- PLC output module troubleshooting.

Ancillaries

• Activities Manual for *Electric Motors and Control Systems*. This manual contains quizzes, practical assignments, and computer-generated simulated circuit analysis assignments.

Quizzes made up of multiple choice, true/false, and completion-type questions are provided for each part of each chapter. These serve as an excellent review of the material presented.

Practical assignments are designed to give the student an opportunity to apply the information covered in the text in a hands-on motor installation.

The Constructor motor control simulation software is included as part of the manual. This special edition of the program contains preconstructed simulated motor control circuits constructed using both NEMA and IEC symbols. The constructor analysis assignments provide students with the opportunity to test the motor control circuits discussed in the text. The constructor simulation engine visually displays power flow to each component and using animation and sound effects; each component will react accordingly once power is supplied.

The constructor troubleshooting mode includes a Test Probe that provides an indication of power or continuity. The test probe leads are inserted into the circuit to determine common preprogrammed motor faults.

• **Instructor's Resources** are available to instructors who adopt *Electric Motors and Control Systems*. They can be found on the Instructor Library on Connect and include: *Answers* to the textbook review questions and the Activities Manual quizzes and assignments.

PowerPoint presentations that feature enhanced graphics along with explanatory text. *Instructional videos* for text motor control circuits.

ACKNOWLEDGMENTS

The efforts of many people are needed to develop and improve a text. Among these people are the reviewers and consultants who point out areas of concern, cite areas of strength, and make recommendations for change. In particular, I would like to acknowledge Don Pelster of Nashville Community College. Don has done an impeccable job of performing a technical edit of the text as well as all the additional Instructor resources.

Page xii

lectric Motors and Control Systems, 3e
 contains the most up-to-date information on electric motor operation, selection, installation, control, and maintenance. The text provides a balance between concepts and applications to offer students an accessible framework to introduce a broad range of motor types and control systems.

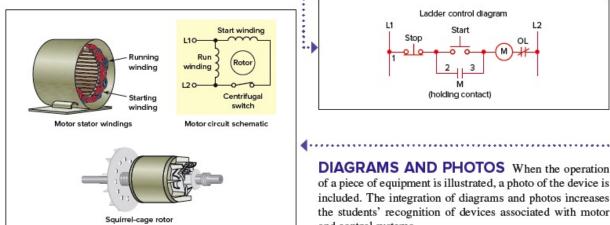
CHAPTER OBJECTIVES provide an outline of the concepts that will be presented in the chapter. These objectives provide a roadmap to students and instructors on what new material will be presented.

CHAPTER OBJECTIVES

This chapter will help you:

......

- Recognize symbols frequently used on motor and control diagrams.
- Differentiate between NEMA and IEC motor control symbols.
- Interpret and construct ladder diagrams.
- Interpret wiring, single-line, and block diagrams.
- Explain the terminal connections for different types of motors.
- Interpret connection schemes used for dual-voltage three-phase motors.
- Interpret information found on motor nameplates.
- Explain the terminology used in motor circuits.

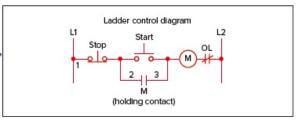


Electric Motors and Control Systems provides...

CIRCUIT LISTS When a new operation of a circuit is presented, a bulleted list is used to summarize the operation. The lists are used in place of paragraphs to provide a more accessible summary of the necessary steps of a motor control operation.

The operation of the circuit can be summarized as follows:

- · Three-wires are run from the start/stop pushbutton station to the starter.
- When the momentary-contact start button is closed, line voltage is applied to the starter coil to energize it.
- The three main M contacts close to apply voltage to the motor.



DIAGRAMS AND PHOTOS When the operation of a piece of equipment is illustrated, a photo of the device is included. The integration of diagrams and photos increases the students' recognition of devices associated with motor and control systems.

Page xiii

•• an engaging

- • • • framework in
- every chapter
- to help students
- master concepts
- and realize
- success beyond
- the classroom.

REVIEW QUESTIONS Each chapter is divided into parts designed to represent individual lessons. These parts provide professors and students the flexibility to pick and choose topics that best represent their needs. Review questions follow each part to reinforce the new concepts that have been introduced.

Part 1 Review Questions

- Does the severity of an electric shock increase or decrease with each of the following changes?
- decrease with each of the following changer? a. A decrease in the source voltage b. A a increase in hody current flaw c. An increase in hody resistance d. A decrease in the length of time of exposure 2. a. Culculate the theoretical body current flow (in amprese and milliampeers) of an electric shock within who comes in contact with a 120 V energy come A decrease in industry of a flow 00.0
- source. Assume a total resistance of 15,000 Ω (skin, body, and ground contacts).
- b. What effect, if any, would this amount of current likely have on the body?

:...

- Normally a 6 volt lantern battery capable of delivering 2A of current is considered safe to handle. W hy?
- Why is AC of a 60 Hz frequency considered to be potentially note dangerous than DC of the same voltage and current value?
- - What circuit fault can result in an arc flash?
- State the piece of electrical safety equipment that should be used to perform each of the following tasks: a. A switching operation where there is a risk of injury to the eyes or face from an electric arr. b. Using a multimeter to verify the line voltage on a three-phase 430 volt system.
- e. Opening a manually operated high-voltage disconre of switch.
- Outline the safety procedure to follow when you are connecting shorting probes across de-energized circuits.
- List three pieces of personal protection equipment required to be worm on most job sites. 11. Explain the way in which safety light curtains
- operate. 12. a. Describe a typical example of point of operation
- light curtain control. Describe a typical example of perimeter access light curtain control.
- 13. What type of safety switch is used to monitor the

TROUBLESHOOTING SCENARIOS These

scenarios are designed to help students develop a systematic approach to trouble shooting that is vital in this course.

	froubleshooting Scenarios				
1.	He at is the greatest energy of a motor. Discuss in what way notestherence to each of the following motor sameplate parameters could cause a motor to overheat: (a) voltage rating; (b) current rating; (c) ambiest importance; (d) duty cycle.	one with the s we beits of a m	6. A summe you have to purchase a motor to replace th one with the specifications shown below. Visit the website of a motor manufacturer and se port on the specifications and price of a seplacement motor.		
2.	Two identical control solay coils are incorsectly				
	connected in series instead of parallel across a	Horsepowe		10	
	230 V source. Discuss how this might affect the operation of the circuit	Voltage		200	
3.	A two-wise magnetic motor control circuit control-	Hertz		60	
	ling a furnace fan uses a thermostat to automatically	Phase		3	
	openue the motor on and off. A single-pole switch is	Full-load an	mperes.	32	
	to be installed next to the sensole thermostat and	RPM		1725	
	wised so that, when closed, it will override the auto-	Farresbe		215T	
	matic control and allow the fan to operate at all times segardless of the thermostat setting. Draw a ladder	Service fac	tor	1.15	
	control diagram of a circuit that will accomplish this.	Rating		40C AMB-CONT	
4	A three-wire magnetic motor control circuit uses	Locked roto	or code	J	
	a senaote start'stop publication station to operate	NEMA desi	gn code		
	the motor on and off. Assume the start button is	Insulation of	iess.		
	pressed but the starter coil does not energize. List	Full-load et	ficiency	85.5	
	the possible causes of the problem.	Power facto	or	76	
5.	How is the control voltage obtained in most motor control circuits?	Enclosure	5	OPEN	

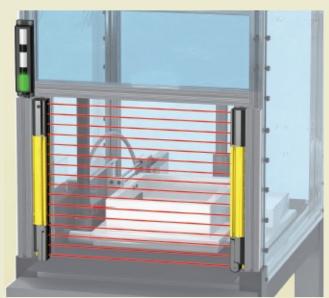
DISCUSSION TOPICS AND CRITICAL THINKING QUESTIONS These

open-ended questions are designed to give students an opportunity to review the material covered in the chapter. These questions cover all the parts presented in each chapter and provide an opportunity for the student to show comprehension of the concepts covered.

Discussion Topics and Critical Thinking Questions 1. Why are contacts from control devices not placed in parallel with loads? 4. The AC squirrel-cage induction motor is the dominant motor to choology in use today. Why? Record all the nameplate data for a given motor and write a short description of what each item specifies. In general, how do NEMA motor standards compase to IEC standards? write a stort description of white said then appendix 3. Search the interment for electric motor constantion diagrams. Record all information given sfor the connection of the following types of motors: a. DC compound motor b. AC single-phase star-voltage induction motor c. AC these-phase two-speed induction motor

CHAPTER ONE

Safety in the Workplace



Banner Engineering

CHAPTER OBJECTIVES

This chapter will help you:

- Identify the electrical factors that determine the severity of an electric shock.
- Describe arc flash hazard recognition and prevention.
- List of general principles of electrical safety including wearing approved protective clothing and using protective equipment.
- Understand the application of different types of electrical machine safety devices.
- Explain the safety aspects of grounding an electrical motor installation.
- Outline the basic steps in a lockout procedure.
- Identify the functions of the different organizations responsible for electrical codes and standards.

Safety is the number one priority in any job. Every year, electrical accidents cause serious injury or death. Many of these casualties are young people just entering the workplace. They are involved in accidents that result from carelessness, from the pressures and distractions of a new job, or from a lack of understanding about electricity. This chapter is designed to develop an awareness of the dangers

associated with electrical power and the potential dangers that can exist on the job or at a training facility.

PART 1 PROTECTING AGAINST ELECTRICAL SHOCK

Electrical Shock

The human body conducts electricity. Even low currents may cause severe health effects. Spasms, burns, muscle paralysis, or death can result, depending on the amount of the current flowing through the body, the route it takes, and the duration of exposure.

The main factor for determining the severity of an electric shock is the amount of electric current that passes through the body. This current is dependent upon the voltage and the resistance of the path it follows through the body.

Electrical **resistance** (*R*) is the opposition to the flow of current in a circuit and is measured in ohms (Ω). The lower the body resistance, the greater the current flow and potential electric shock hazard. Body resistance can be divided into external (skin resistance) and internal (body tissues and blood stream resistance). Dry skin is a good insulator; moisture lowers the resistance of skin, which explains why shock intensity is greater when the hands are wet. Internal resistance is low owing to the salt and moisture content of the blood. There is a wide degree of variation in body resistance. A shock that may be fatal to one person may cause only brief discomfort to another. Typical body resistance values are:

- Dry skin—100,000 to 600,000 Ω
- Wet skin—1.000 Ω
- Internal body (hand to foot)—400 to 600Ω
- Ear to ear— 100Ω

Thin or wet skin is much less resistant than thick or dry skin. When skin resistance is low, the current may cause little or no skin damage but severely burn internal organs and tissues. Conversely, high skin resistance can produce severe skin burns but prevent the current from entering the body.

Voltage (*E*) is the pressure that causes the flow of electric current in a circuit and is measured in units called volts (V). The amount of voltage that is dangerous to life varies with each individual because of differences in body resistance and heart conditions. Generally, any voltage *above 30 V* is considered dangerous.

Electric **current** (*I*) is the rate of flow of electrons in a circuit and is measured in amperes (A) or milliamperes (mA). One milliampere is one-thousandth of an ampere. The amount of current flowing through a person's body depends on the voltage and resistance. Body current can be calculated using the following Ohm's law formula:

 $Current = \frac{Voltage}{Resistance}$

Page 2

If you came into direct contact with 120 volts and your body resistance was 100,000 ohms, then the current that would flow would be:

$$I = \frac{120 \text{ V}}{100,000 \Omega}$$

$$= 0.0012 \text{ A}$$

$$= 1.2 \text{ mA } (0.0012 \times 1,000)$$
This is just about at the threshold of perception, so it would produce only a tingle.

If you were sweaty and barefoot, then your resistance to ground might be as low as 1,000 ohms. Then the current would be:

$$I = \frac{120 \text{ V}}{1,000 \Omega} = 0.12 \text{ A} = 120 \text{ mA}$$
This is a lethal shock, capable of producing ventricular fibriliation (rapid irregular contractions of the heart) and death!

Voltage is not as reliable an indication of shock intensity because the body's resistance varies so widely that it is impossible to predict how much current will result from a given voltage. The amount of current that passes through the body and the length of time of exposure are perhaps the two most reliable criteria of shock intensity. Once current enters the body, it follows through the circulatory system in preference to the external skin. Figure 1-1 illustrates the relative magnitude and effect of electric current. It doesn't take much current to cause a painful or even fatal shock. A current of 1 mA (1/1000 of an ampere) can be felt. A current of 10 mA will produce a shock of sufficient intensity to prevent voluntary control of muscles, which explains why, in some cases, the victim of electric shock is unable to release grip on the conductor while the current is flowing. A current of 100 mA passing through the body for a second or longer can be fatal. Generally, any current flow *above 0.005 A, or 5 mA*, is considered dangerous.

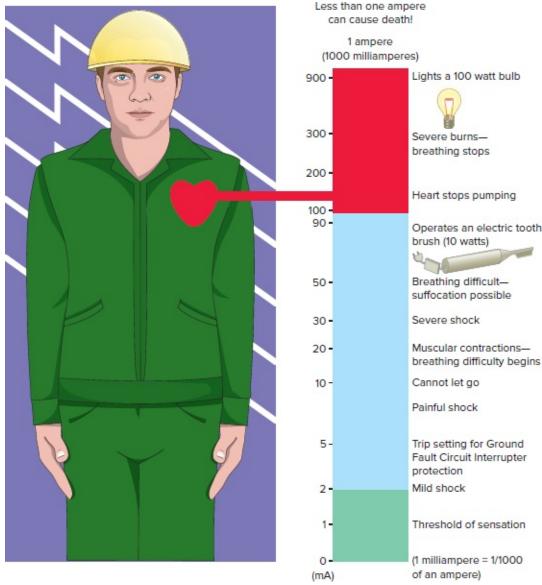


Figure 1-1 Relative magnitude and effect of electric current on the body.

A 1.5 V flashlight cell can deliver more than enough current to kill a human being, yet it is safe to handle. This is because the resistance of human skin is high enough to limit greatly the flow of electric current. In lower voltage circuits, resistance restricts current flow to very low values. Therefore, there is little danger of an electric shock. Higher voltages, on the other hand, can force enough current though the skin to produce a shock. The danger of harmful shock increases as the voltage increases.

The pathway through the body is another factor influencing the effect of an electric shock. For example, a current from hand to foot, which passes through the heart and part of the central nervous system, is far more dangerous than a shock between two points on the same arm (Figure 1-2).

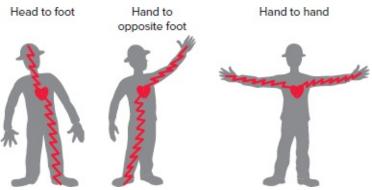


Figure 1-2 Typical electric current pathways that stop normal pumping of the heart.

AC (alternating current) of the common 60 Hz frequency is three to five times more dangerous than DC (direct current) of the same voltage and current value. DC tends to cause a convulsive contraction of the muscles, often forcing the victim away from further current exposure. The effects of AC on the body depend to a great extent on the frequency: low-frequency currents (50–60 Hz) are usually more dangerous than high-frequency currents. AC causes muscle spasm, often "freezing" the hand (the most common part of the body to make contact) to the circuit. The fist clenches around the current source, resulting in prolonged exposure with severe burns.

The most common electric-related injury is a burn. The major types of burns:

- **Electrical burns,** which are a result of electric current flowing through the tissues or bones. The burn itself may be only on the skin surface or deeper layers of the skin may be affected.
- **Arc burns,** which are a result of an extremely high temperature caused by an electric arc (as high as 35,000°F) in close proximity to the body. Electric arcs can occur as a result of poor electrical contact or failed insulation.
- **Thermal contact burns,** which are a result of the skin coming in contact with the hot surfaces of overheated components. They can be caused by contact with objects dispersed as a result of the blast associated with an electric arc.

If a person does suffer a severe shock, it is important to free the victim from the current as quickly as can be done safely. Do not touch the person until the electric power is turned off. You cannot help by becoming a second victim. The victim should be attended to immediately by a person trained in CPR (cardiopulmonary resuscitation). Page 4

Arc Flash Hazards

An **arc flash** is the ball of fire that explodes from an electrical **short circuit** between one exposed live conductor and another conductor or to ground. The arc flash creates an enormous amount of energy (Figure 1-3) that can damage equipment and cause severe injury or loss of life.



Figure 1-3 Arc flash. Photo Courtesy of Honeywell, www.honeywell.com

An arc flash can be caused by dropped tools, unintentional contact with electrical systems, or the buildup of conductive dust, dirt, corrosion, and particles.

Electrical short circuits are either bolted faults or arcing faults. A **bolted fault** is current flowing through bolted bus bars or other electric conductors. An **arcing fault** is current flowing through the air. Because air offers opposition to electric current flow, the arc fault current is always lower than the bolted fault current. An **arc blast** is a flash that causes an explosion of air and metal that produces dangerous pressure waves, sound waves, and molten steel.

In order to understand the hazards associated with an arc flash incident, it is important to understand the difference between an arcing short circuit and a bolted short circuit. A bolted short circuit occurs when the normal circuit current bypasses the load through a very low conductive path, resulting in current flow that can be hundreds or thousands of times the normal load current. In this case, assuming all equipment remains intact, the fault energy is contained within the conductors and equipment, and the power of the fault is dissipated throughout the circuit from the source to the short. All equipment needs to have adequate interrupting ratings to safely contain and clear the high fault currents associated with bolted faults.

In contrast, an arcing fault is the flow of current through a higher-resistance medium, typically the air, between phase conductors or between phase conductors and neutral or ground. Arcing fault currents can be extremely high in current magnitude approaching the bolted short-circuit current but are typically between 38 and 89 percent of the bolted fault. The inverse characteristics of typical overcurrent protective devices generally result in substantially longer clearing times for an arcing fault due to the lower fault values.

Eighty percent of electrical workplace accidents are associated with arc flash and involve burns or injuries caused by intense heat or showers of molten metal or debris. In addition to toxic smoke, shrapnel, and shock waves, the creation of an arc flash produces an intense flash of blinding light. This flash is capable of causing immediate vision damage and can increase a worker's risk of future vision impairment.

An arc flash hazard exists when a person interacts with equipment in a way that could cause an electric arc. Such tasks may include testing or troubleshooting, application of temporary protective grounds, or the opening or closing of power circuit breakers as illustrated in Figure 1-4. Arcs can produce temperature four times hotter than the surface of the sun. To address this hazard, safety standards such as National Fire Protection Association (NFPA) 70E have been developed to minimize arc flash hazards. The NFPA standards require that any panel likely to be serviced by a worker be surveyed and labeled. Injuries can be avoided with training; with proper work practices; and by using protective face shields, hoods, and clothing that are NFPA-compliant.



Figure 1-4 An arc flash hazard exists when a person interacts with equipment. Chemco Electrical Contractors Ltd.

Personal Protective Equipment

Construction and manufacturing worksites, by nature, are potentially hazardous places. For this reason, safety has become an increasingly large factor in the working environment. The electrical industry, in particular, regards **safety** to be unquestionably the most single important priority because of the hazardous nature of the business. A safe operation depends largely upon all personnel being informed and aware of potential hazards. Safety signs and tags indicate areas or tasks that can pose a hazard to personnel and/or equipment. Signs and tags may provide warnings specific to the hazard, or they may provide safety instructions (Figure 1-5).